

Link4 tester ver.1

4節リンクシミュレータ

以下の機能を持つ

1. 構成モードでリンクの長さや節点位置を変更できる
2. シミュレーションモードで駆動リンクを動かすことができる
3. 取り消しモードで初期リンクに戻すことができる
4. ビームの長さは基本単位の整数倍である。初期値はビームの長さが1,基本単位はその1/5である
5. リンク先端をトレースすることができる
6. 計算精度が不十分の場合には節点が赤くなる
7. リンク構成をファイルにセーブ・ロードできる

```
In[697]:= ClearAll["Global`*"];
$IterationLimit = 20;
worksize = 400;
baseUnit = bU = 1.;
partition = 1 / 5;
psize = bU * partition;
(*Off[FindRoot]*)
(* find a cross point between the circle centered q1 and the circle centered q2, where
   f: initial guess, q1: point-1, q2: point-2, r1: radius of q1, r2: radius of q2 *)
rf[{f_, q1_, q2_}, {r1_, r2_}] := (
  z = {};
  {x, y} /. Check[FindRoot[{(x - q1[[1]])^2 + (y - q1[[2]])^2 == r1^2, (x - q2[[1]])^2 +
    (y - q2[[2]])^2 == r2^2}, {{x, f[[1]]}, {y, f[[2]]}}, z = Red; {x, y} -> f], z]);
exsave[data_] := Put[data, FileNameJoin[{NotebookDirectory[], "link-data.txt"}]];
exload := Get[FileNameJoin[{NotebookDirectory[], "testfile"}]];

reset = xload = xsave = False; trace = {}; last = {}; lbl = "↑";
mstyle = {Appearance -> "Palette", BaselinePosition -> Center};
menu = Row[{
  Row[{SetterBar[Dynamic[mode],
    {construct -> "☐", simulate -> "⌋"}, BaseStyle -> {FontSize -> 20}, mstyle],
    Button["☐", mode = construct; reset = True, BaseStyle -> {FontSize -> 22}, mstyle],
    ActionMenu["f", {Save -> (xsave = True), Load -> (exload[gload]; xload = True)},
      BaseStyle -> {FontSize -> 18}, mstyle, Enabled -> Dynamic[mode == construct]],
    Button[Dynamic@lbl, If[lbl == "↑", pencil = True; lbl = "↓",
      pencil = False; lbl = "↑"], BaseStyle -> {FontSize -> 22}, mstyle]]],

  DynamicModule[{t},
    Animate[
      If[ControlActive[True, False],
        If[pencil,
          If[last != out, AppendTo[trace, Point[out]]; last = out], trace = {}; last = {}];
        pt = {Sin[t], Cos[t]};
        Deploy@Graphics[{Circle[], Locator[Dynamic[pt, (pt = Normalize[#]) &]]},
          PlotRange -> 1.2, ImageSize -> 60], {t, 0, 2 Pi, Pi / 20},
        AnimationRunning -> False, ControlPlacement -> Right, LabelStyle -> Opacity[0]]],
    Spacer[4]];

DynamicModule[
  {p1 = {0, 0}, p2 = {0, bU}, p3 = {bU, 0},
    p4 = {bU, bU}, p5 = {1.5 bU, bU}, p6 = {bU, 1.5 bU}},

  g = Dynamic[Switch[mode,
    construct, (
      locatorStatus = True;
      If[reset, {p1, p2, p3, p4, p5, p6} =
        {{0, 0}, {0, bU}, {bU, 0}, {bU, bU}, {1.5 bU, bU}, {bU, 1.5 bU}}; reset = False];
```

```

If[xload, {p1, p2, p3, p4, p5, p6} = exload; xload = False];
If[xsave, exsave[{p1, p2, p3, p4, p5, p6}]; xsave = False];
{r1, r2, r3, r4, r5, r6} =
  Map[Round[Norm[#], psize] &, {p1 - p2, p3 - p4, p2 - p4, p2 - p5, p3 - p6, p1 - p3}];
{ReleaseHold@Map[Locator[Dynamic[#], Enabled → locatorStatus] &,
  {Hold@p1, Hold@p2, Hold@p3, Hold@p4, Hold@p5, Hold@p6}],
  Map[Line, {{p1, p2}, {p3, p6}, {p2, p5}, {p1, p3}}]}],
simulate, (
  locatorStatus = False;
  p2 = r1 * pt + p1;
  {p4, st2} = rf[{p4, p2, p3}, {r3, r2}];
  out = p5 = r4 / r3 (p4 - p2) + p2;
  p6 = r5 / r2 (p4 - p3) + p3;
  {Locator[p1, Background → Green], Locator[p2], Locator[p3],
    Locator[p4, Background → Dynamic@st2], Locator[p5], Locator[p6],
    Line[{p1, p2}], Line[{p3, p6}], Line[{p2, p5}], Line[{p1, p3}]}]
];

targetpain = Framed@Deploy@Graphics[{g, Dynamic@trace},
  ImageSize → {1.8 worksize, worksize}, PlotRange → {{-1 bU, 3 bU}, {-1 bU, 2 bU}}];
Framed@Column[{menu, targetpain}]

```